

DE LA RECHERCHE À L'INDUSTRIE



A Staggered Mimetic ALE Scheme for Hydrodynamics (SMASH) ensuring geometric and energetic consistency

Thibaud Vazquez-Gonzalez¹

Antoine Llor¹ and Christophe Fochesato¹

¹ CEA, DAM, DIF, F-91297 Arpajon, France,

MULTIMAT 2015

- ▶ Scientific context : ALE schemes and numerical mimetism
- ▶ Discrete derivation of the scheme
 - Discretization of fields and transport
 - Discrete action integral and Euler–Lagrange equations
 - Global strategy of derivation
 - Main steps of scheme
- ▶ Numerical tests
 - 1D indifference to implicit–explicit advection
 - 2D indifference to grid motion strategy
 - 1D–2D versatility in the choice of grid velocity
- ▶ Conclusions and perspectives

Simulation of **applied, non-stationnary, and compressible single-fluid flows** (shocks and grid deformations)

The numerical scheme must comply with several constraints :

- ▶ **Arbitrary** evolution of the computational domain and grid
- ▶ **Exact** conservation of mass, momentum and total energy
- ▶ **Thermodynamically consistent** capture of pressure work (hence entropy)
- ▶ **Robustness and stability** in presence of shocks and mesh deformations
- ▶ **Compatibility** with other physics and competing stiff phenomena

Usually, simulation of continuum dynamics use Eulerian or Lagrangian reference frames

- ▶ Eulerian : simulations on fixed grids → stable and robust results but diffusive schemes
- ▶ Lagrangian : grids evolve with material velocities → less diffusive but critical grid distortions when simulating realistic flows

These combined features have encouraged the use of ALE (Arbitrary Lagrangian Eulerian) methods in CFD.

Two main types of ALE approaches

- ▶ Indirect ALE : coupling a Lagrangian evolution phase to a remapping procedure after each or several time steps
 - ↔ results more robust and less diffusive but conservation issues in staggered mesh and computational cost of remapping in 2–3D
- ▶ Direct ALE : grid subjected to arbitrary motions
 - ↔ mass, momentum, and energy fluxes are taken into account directly in the discrete evolution equations
 - ↔ grid node velocities are given a priori (user defined), and possibly constraint by boundary conditions, Lagrangian limit, tracking of characteristics, etc . . .

Application of least action principle to discrete action integral

- ▶ Special case of broad class of **numerical mimetism** : transposing as accurately as possible some critically important physical constraints into discrete equations
- ▶ Use of mimicking schemes rather limited in CFD
 - ↔ non-holonomic constraints with mass and entropy advections and non-symmetric form of discrete Lagrangian can lead to non-conservative evolution equations
- ▶ However, application of least action principle is well motivated in CFD
 - Capture of the pressure work done in a **thermodynamical consistent** way
 - Derivation using only algebraic quantities instead of the usual PDEs
 - Yields powerful numerical schemes for long time integrations when applied to Hamiltonian systems

Reminders on the least action principle :

- ▶ Start from **continuous Lagrangian** of hydrodynamics :

$$\mathcal{L} = \frac{1}{2} \rho \mu_i \mu_i - \rho e(\rho) + \phi [\partial_t \rho + (\rho u_i)_{,i}]$$

- ▶ Application of least action principle $\delta \mathcal{A} = \iint \left[\frac{\partial \mathcal{L}}{\partial \phi} \delta \phi + \frac{\partial \mathcal{L}}{\partial u_i} \delta u_i + \frac{\partial \mathcal{L}}{\partial \rho} \delta \rho \right] d^3 \mathbf{x} dt$
- ▶ Evolution equations for **mass and momentum in the local grid frame**

$$\partial_t \rho + (\rho u_i)_{,i} = 0, \tag{1a}$$

$$\partial_t (\rho \mu_i) + (\rho \mu_i u_j)_{,j} = -P_{,i} \tag{1b}$$

where \mathbf{w} , \mathbf{u} and $\boldsymbol{\mu} = \mathbf{u} + \mathbf{w}$ are resp. grid velocity, relative velocity and absolute velocity

The approach developed here tends to regroup

- ▶ **Direct ALE formalism** → robustness and stability in presence of strong shocks and deformations
- ▶ **Least action principle** → thermodynamically consistent capture of pressure work

Similar combinations already tested :

- ▶ ALE + LAP → [Koo, 2000]
- ▶ Incomp. Euler + symplectic LAP → [Pavlov, 2011]

- ▶ Scientific context : ALE schemes and numerical mimetism
- ▶ Discrete derivation of the scheme
 - Discretization of fields and transport
 - Discrete action integral and Euler–Lagrange equations
 - Global strategy of derivation
 - Main steps of scheme
- ▶ Numerical tests
 - 1D indifference to implicit–explicit advection
 - 2D indifference to grid motion strategy
 - 1D–2D versatility in the choice of grid velocity
- ▶ Conclusions and perspectives

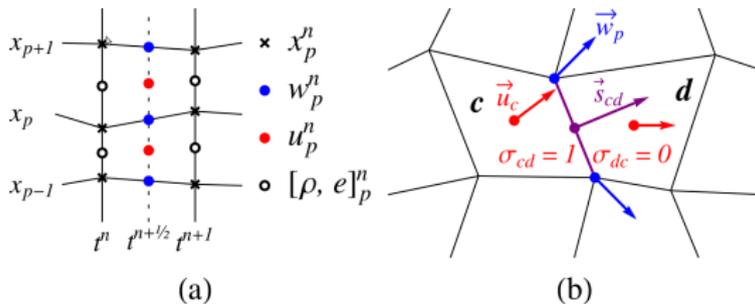


FIGURE: (a) 1D representation of a space-time element with the localisation of thermodynamic quantities and velocities; (b) Space localisation of grid and relative-to-grid velocities, and of the corresponding upwinding coefficients.

Notations :

- ▶ \mathbf{w} grid velocity
- ▶ \mathbf{u} fluid velocity relative to the grid
- ▶ $\boldsymbol{\mu} = \mathbf{u} + \mathbf{w}$ absolute velocity of the fluid
- ▶ \mathbf{s}_{cd}^n outward pointing vector to boundary between c — d (magnitude given by the area of the c — d)
- ▶ $\sigma_{cd}^{n+1/2} = \frac{1}{2} [1 + \text{sign}(\mathbf{s}_{cd}^{n+1/2} \cdot \mathbf{u}_c^{n+1/2})]$ off-centering factor of transport from c to d
- ▶ ρ and e resp. density and internal energy
- ▶ $\Delta t^{n+1/2} = t^{n+1} - t^n$ time step between t^n and t^{n+1}

Internal energy

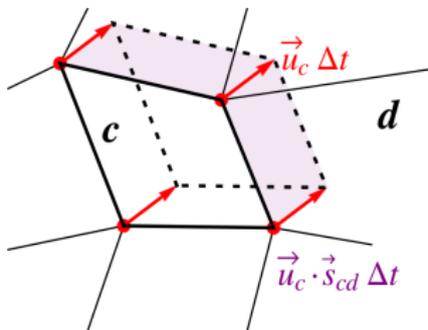
$$\iint \rho e(\rho) d^3x dt \rightsquigarrow \sum_n \sum_c \Delta t^n V_c^n \rho_c^n e_c^n . \quad (2)$$

Kinetic energy

$$\iint \frac{1}{2} \rho (u_i + w_i)^2 d^3x dt \rightsquigarrow \sum_n \sum_c \Delta t^{n-1/2} V_c^n \frac{1}{2} \rho_c^n (\mu_c^{n-1/2})^2 . \quad (3)$$

Remarks :

- ▶ $\Delta t^n = \frac{1}{2} (\Delta t^{n+1/2} + \Delta t^{n-1/2})$
- ▶ $\mu_c^{n+1/2} = \mathbf{u}_c^{n+1/2} + \mathbf{w}_c^{n+1/2}$ with $\mathbf{w}_c^{n+1/2} = \frac{1}{|\mathcal{P}(c)|} \sum_{\mathcal{P}(c)} \mathbf{w}_p^{n+1/2}$
- ▶ $\mu_c^{n-1/2}$ is $\Delta t^{n-1/2}/2$ behind density ρ_c^n allows to factorize ρ_c^n when obtaining the discrete absolute velocity equation
- ▶ Full midpoint rule in time in the Lagrangian limit as $V_c^n \rho_c^n = V_c^{n+1/2} \rho_c^{n+1/2}$



$$V_c^{n+1} \rho_c^{n+1} - V_c^n \rho_c^n - \Delta t^{n+1/2} \sum_{d \in \mathcal{D}(c)} (\sigma_{dc}^{n+1/2} \mathbf{s}_{dc}^{n+1/2} \cdot \mathbf{u}_d^{n+1/2} \rho_d^{n+1} - \sigma_{cd}^{n+1/2} \mathbf{s}_{cd}^{n+1/2} \cdot \mathbf{u}_c^{n+1/2} \rho_c^{n+1}) = 0. \quad (4)$$

Remarks on (4) :

- ▶ **Simple first-order-in-space-and-time upwind** scheme for the computation of the mass fluxes between cell c and d
- ▶ ρ must be $\Delta t^{n-1/2}/2$ ahead of μ as already observed for Ec
 \hookrightarrow implicit mass transport but explicit absolute velocity equation
- ▶ Mass transport as a rudimentary version of Lagrange plus remap approaches
- ▶ 1st accuracy is not incompatible with 2nd order of Ei and Ec but acceptable **as a starting point**
 \hookrightarrow motion relative to the grid only a **correction** over the motion captured by the grid

Discrete action integral of the system

$$\mathcal{A} = \sum_n \sum_c \left\{ \Delta t^{n-1/2} V_c^n \frac{1}{2} \rho_c^n (\mu_c^{n-1/2})^2 - \Delta t^n V_c^n \rho_c^n e_c^n \right. \\ \left. + \phi_c^{n+1/2} \left[V_c^{n+1} \rho_c^{n+1} - V_c^n \rho_c^n - \Delta t^{n+1/2} \sum_{d \in \mathcal{D}(c)} (\sigma_{dc}^{n+1/2} \mathbf{s}_{dc}^{n+1/2} \cdot \mathbf{u}_d^{n+1/2} \rho_d^{n+1} - \sigma_{cd}^{n+1/2} \mathbf{s}_{cd}^{n+1/2} \cdot \mathbf{u}_c^{n+1/2} \rho_c^{n+1}) \right] \right\}.$$

with the least action principle

$$\delta \mathcal{A} = \sum_n \sum_c \left(\frac{\partial \mathcal{A}}{\partial \phi_c^{n+1/2}} \delta \phi_c^{n+1/2} + \frac{\partial \mathcal{A}}{\partial \mathbf{u}_c^{n-1/2}} \cdot \delta \mathbf{u}_c^{n-1/2} + \frac{\partial \mathcal{A}}{\partial \rho_c^n} \delta \rho_c^n \right) = 0. \quad (5)$$

yields the discrete Euler–Lagrange equations

$$V_c^{n+1} \rho_c^{n+1} - V_c^n \rho_c^n + \Delta t^{n+1/2} \sum_{d \in \mathcal{D}(c)} (\sigma_{cd}^{n+1/2} \mathbf{s}_{cd}^{n+1/2} \cdot \mathbf{u}_c^{n+1/2} \rho_c^{n+1} - \sigma_{dc}^{n+1/2} \mathbf{s}_{dc}^{n+1/2} \cdot \mathbf{u}_d^{n+1/2} \rho_d^{n+1}) = 0,$$

$$V_c^n \mu_c^{n-1/2} = \sum_{d \in \mathcal{D}(c)} \sigma_{cd}^{n-1/2} \mathbf{s}_{cd}^{n-1/2} (\phi_d^{n-1/2} - \phi_c^{n-1/2}),$$

$$\phi_c^{n+1/2} - \phi_c^{n-1/2} = -\Delta t^n (e_c^n + P_c^n / \rho_c^n) - \Delta t^{n-1/2} \frac{1}{2} ((\mathbf{u}_c^{n-1/2})^2 - (\mathbf{w}_c^{n-1/2})^2).$$

The numerical scheme must respect several important properties

- ▶ Elimination of Lagrange multiplier ϕ
- ▶ Fully conservative in mass, momentum and total energy
- ▶ Only pressure forces are retained
- ▶ Explicit evolution of absolute velocity equation (or at least linearly implicit)

In order to preserve these properties, the global strategy of this work is

- ▶ Cancel discrete numerical residues **at the scheme's order** (i.e. 2nd order in Lagrangian limit but only 1st order in Eulerian limit)
- ▶ Introduction of so-called **time flux terms** [CSTS, submitted] when necessary
- ▶ Correction of evolution equations **as close as possible** to the variational equations
- ▶ Internal energy equation derived from **conservation of total energy**
↪ only physical and residual fluxes are left when summing kinetic and internal energies

1) **Explicit** evolution of absolute velocity

$$V_c^n \rho_c^n (\mu_c^{n+1/2} - \mu_c^{n-1/2}) = -\Delta t^n \sum_{d \in \mathcal{D}(c)} \frac{1}{2} (1 + \sigma_{cd}^{n-1/2} - \sigma_{dc}^{n-1/2}) s_{cd}^{n-1/2} (\rho_d^n - \rho_c^n) \\ + \Delta t^{n-1/2} \sum_{d \in \mathcal{D}(c)} \sigma_{dc}^{n-1/2} s_{dc}^{n-1/2} \cdot \mathbf{u}_d^{n-1/2} \rho_d^n (\mu_d^{n-1/2} - \mu_c^{n-1/2}). \quad (7)$$

2) Choice of a grid velocity $\mathbf{w}_p^{n+1/2}$ 3) **Linearly implicit** evolution of mass transport

$$V_c^{n+1} \rho_c^{n+1} - V_c^n \rho_c^n = \Delta t^{n+1/2} \sum_{d \in \mathcal{D}(c)} (\sigma_{dc}^{n+1/2} s_{dc}^{n+1/2} \cdot \mathbf{u}_d^{n+1/2} \rho_d^{n+1} - \sigma_{cd}^{n+1/2} s_{cd}^{n+1/2} \cdot \mathbf{u}_c^{n+1/2} \rho_c^{n+1}) \quad (8)$$

4) **Linearly implicit** evolution of internal energy

$$V_c^{n+1} \rho_c^{n+1} e_c^{n+1/2} - V_c^n \rho_c^n e_c^n = -\frac{1}{2} \Delta t^{n+1/2} [P+Q]_c^n \langle \nabla \cdot \boldsymbol{\mu} \rangle_c^{n+1/4} - \frac{(\Delta t^{n+1/2} - \Delta t^{n-1/2})}{4} [P+Q]_c^n (\langle \nabla \cdot \boldsymbol{\mu} \rangle_c^{n+1/4} - \langle \nabla \cdot \boldsymbol{\mu} \rangle_c^{n-1/4}) \\ - \Delta t^{n+1/2} \sum_{d \in \mathcal{D}(c)} (\sigma_{cd}^{n+1/2} s_{cd}^{n+1/2} \cdot \mathbf{u}_c^{n+1/2} \rho_c^{n+1} e_c^{n+1/2} - \sigma_{dc}^{n+1/2} s_{dc}^{n+1/2} \cdot \mathbf{u}_d^{n+1/2} \rho_d^{n+1} e_d^{n+1/2}) \\ - \frac{1}{2} \Delta t^{n+1/2} \sum_{d \in \mathcal{D}(c)} \sigma_{cd}^{n+1/2} s_{cd}^{n+1/2} \cdot \mathbf{u}_c^{n+1/2} \rho_c^{n+1} ((\mu_d^{n+1/2})^2 - (\mu_c^{n+1/2})^2) \\ + \frac{1}{2} \Delta t^{n-1/2} \sum_{d \in \mathcal{D}(c)} \sigma_{cd}^{n-1/2} s_{cd}^{n-1/2} \cdot \mathbf{u}_c^{n-1/2} \rho_c^n (\mu_d^{n-1/2} - \mu_c^{n-1/2}) \cdot (\mu_d^{n+1/2} + \mu_d^{n-1/2}) \quad (9)$$

with

$$e_c^{n+1/2} = e_c^{n+1} + \frac{1}{2} \frac{\Delta t^{n+1/2}}{V_c^{n+1} \rho_c^{n+1}} [P+Q]_c^{n+1} \langle \nabla \cdot \boldsymbol{\mu} \rangle_c^{n+3/4},$$

$$\langle \nabla \cdot \boldsymbol{\mu} \rangle_c^{n\pm 1/4} = \sum_{d \in \mathcal{D}(c)} \left(\frac{1}{2} (1 + \sigma_{cd}^{n-1/2} - \sigma_{dc}^{n-1/2}) s_{cd}^{n-1/2} \cdot \boldsymbol{\mu}_c^{n\pm 1/2} + \frac{1}{2} (1 - \sigma_{cd}^{n-1/2} + \sigma_{dc}^{n-1/2}) s_{cd}^{n-1/2} \cdot \boldsymbol{\mu}_d^{n\pm 1/2} \right).$$

Solving a linearly implicit system for iSMASH with a total number of cells I involves

- ▶ 1D : tridiagonal decomposition (algorithmic complexity $\mathcal{O}(3I)$)
- ▶ 2D : band matrix decomposition (algorithmic complexity $\mathcal{O}(I\sqrt{I})$)

For performance purposes, we propose an explicit version of iSMASH scheme

- ▶ **Same** discrete action integral than iSMASH
- ▶ Approximation of an explicit mass transport **once variational equations are obtained** (numerical residue of this approximation is **at the scheme's order**)
- ▶ eSMASH numerical scheme obtained by using the **same global strategy of derivation** as iSMASH

1) **Explicit** evolution of absolute velocity

$$V_c^n \rho_c^n (\mu_c^{n+1/2} - \mu_c^{n-1/2}) = -\Delta t^n \sum_{d \in \mathcal{D}(c)} \frac{1}{2} (1 + \sigma_{cd}^{n-1/2} - \sigma_{dc}^{n-1/2}) s_{cd}^{n-1/2} (\rho_d^n - \rho_c^n) \\ + \Delta t^{n-1/2} \sum_{d \in \mathcal{D}(c)} \sigma_{dc}^{n-1/2} s_{dc}^{n-1/2} \cdot \mathbf{u}_d^{n-1/2} \rho_d^{n-1} (\mu_d^{n-1/2} - \mu_c^{n-1/2}). \quad (10)$$

2) Choice of a grid velocity $\mathbf{w}_p^{n+1/2}$ 3) **Explicit** evolution of mass transport

$$V_c^{n+1} \rho_c^{n+1} - V_c^n \rho_c^n = \Delta t^{n+1/2} \sum_{d \in \mathcal{D}(c)} (\sigma_{dc}^{n+1/2} s_{dc}^{n+1/2} \cdot \mathbf{u}_d^{n+1/2} \rho_d^n - \sigma_{cd}^{n+1/2} s_{cd}^{n+1/2} \cdot \mathbf{u}_c^{n+1/2} \rho_c^n) \quad (11)$$

4) **Explicit** evolution of internal energy

$$V_c^{n+1} \rho_c^{n+1} e_c^{n+1} - V_c^n \rho_c^n e_c^{n+1/2} = -\frac{1}{2} \Delta t^{n+1/2} [P + Q]_c^{n+1} \langle \nabla \cdot \boldsymbol{\mu} \rangle_c^{n+3/4} \\ - \frac{(\Delta t^{n+1/2} - \Delta t^{n-1/2})}{4} [P + Q]_c^n (\langle \nabla \cdot \boldsymbol{\mu} \rangle_c^{n+1/4} - \langle \nabla \cdot \boldsymbol{\mu} \rangle_c^{n-1/4}) \\ - \Delta t^{n+1/2} \sum_{d \in \mathcal{D}(c)} (\sigma_{cd}^{n+1/2} s_{cd}^{n+1/2} \cdot \mathbf{u}_c^{n+1/2} \rho_c^n e_c^{n+1/2} - \sigma_{dc}^{n+1/2} s_{dc}^{n+1/2} \cdot \mathbf{u}_d^{n+1/2} \rho_d^n e_d^{n+1/2}) \\ - \frac{1}{2} \Delta t^{n+1/2} \sum_{d \in \mathcal{D}(c)} \sigma_{cd}^{n+1/2} s_{cd}^{n+1/2} \cdot \mathbf{u}_c^{n+1/2} \rho_c^n ((\mu_d^{n+1/2})^2 - (\mu_c^{n+1/2})^2) \\ + \frac{1}{2} \Delta t^{n-1/2} \sum_{d \in \mathcal{D}(c)} \sigma_{cd}^{n-1/2} s_{cd}^{n-1/2} \cdot \mathbf{u}_c^{n-1/2} \rho_c^{n-1} (\mu_d^{n-1/2} - \mu_c^{n-1/2}) \cdot (\mu_d^{n+1/2} + \mu_d^{n-1/2}) \quad (12)$$

with

$$e_c^{n+1/2} = e_c^n - \frac{1}{2} \frac{\Delta t^{n+1/2}}{V_c^n \rho_c^n} [P + Q]_c^n \langle \nabla \cdot \boldsymbol{\mu} \rangle_c^{n+1/4},$$

- ▶ Scientific context : ALE schemes and numerical mimetism
- ▶ Discrete derivation of the scheme
 - Discretization of fields and transport
 - Discrete action integral and Euler–Lagrange equations
 - Global strategy of derivation
 - Main steps of scheme
- ▶ Numerical tests
 - 1D indifference to implicit–explicit advection
 - 2D indifference to grid motion strategy
 - 1D–2D versatility in the choice of grid velocity
- ▶ Conclusions and perspectives

Behavior of numerical schemes analyzed by performing several usual test cases involving **shocks and advections** (Sod, Sedov and Triple point tests)

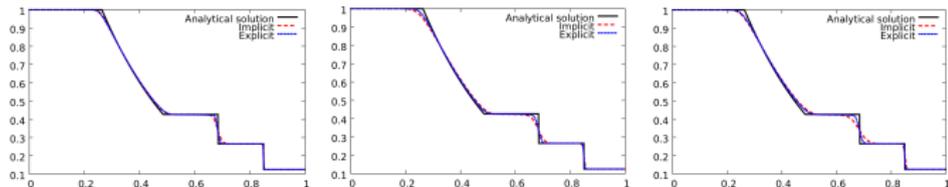
- ▶ In 1D for indifference to implicit (iSMASH) or explicit (eSMASH) advection
- ▶ In 2D for indifference to grid motion strategy (only eSMASH scheme)
- ▶ In 2D for versatility in the choice of grid velocity (only eSMASH)

In all test case results

- ▶ Fluid supposed to be a **perfect gas** $P = (\gamma - 1)\rho e$ with γ the isentropic coefficient
- ▶ Test results are mostly density profiles (velocity and pressure strongly correlated to density)
- ▶ Optimal values of artificial viscosity $P \rightarrow P + Q$ where $a_1 = 0.5$ and $a_2 = \frac{\gamma+1}{2}$ [Lew, 2003]
- ▶ Time step of simulation bounded by **usual CFL condition** (sound velocity and advection)

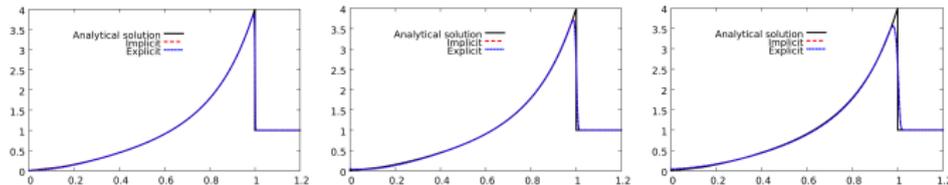
1D tests to indifference to implicit vs explicit advection

Sod's shock tube :

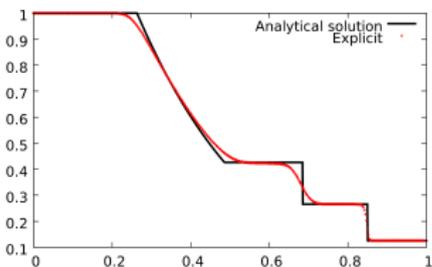
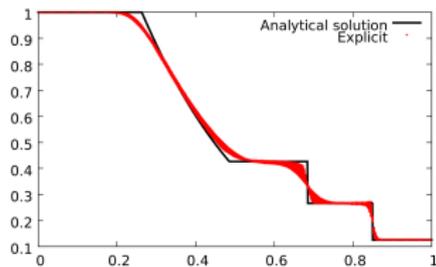
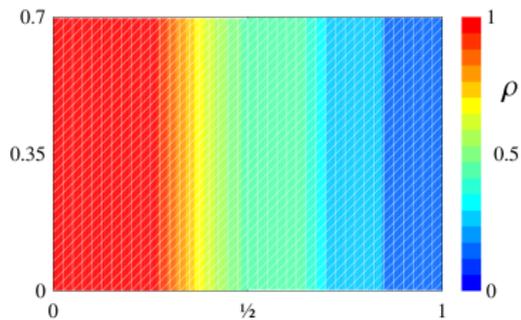
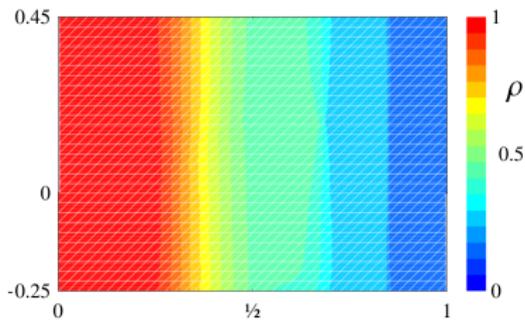
Left : $w = 0$ Center : $w = 2.2$ Right : $w = -1.2$  $I = 1000$ cells, $CFL = 0.8$ for both implicit and explicit advections

Plane Sedov's blast

wave :

Left : $w = 0$ Center : $w = 1.2$ Right : $w = -1.2$  $I = 1000$ cells, $CFL = 0.9$ for both implicit and explicit advections

2D tests to indifference to grid motion strategy



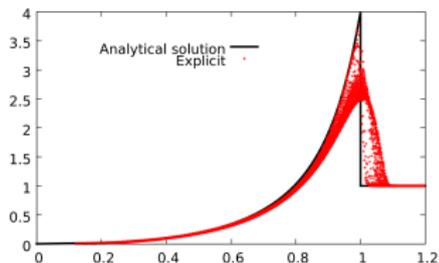
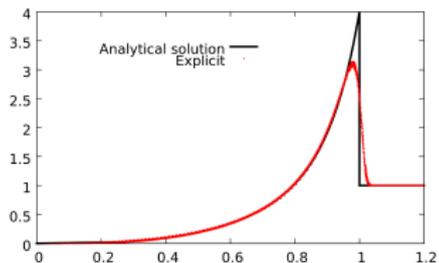
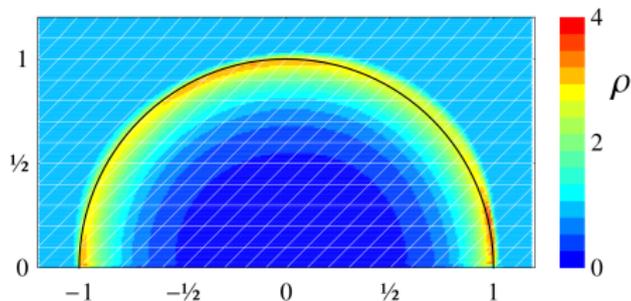
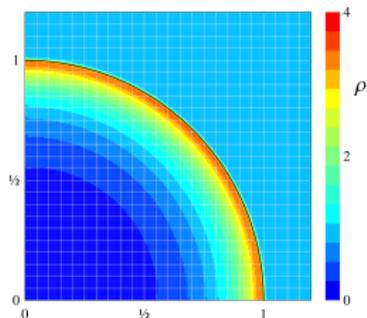
l 400x280

400x280

w $w_x = 5y, w_y = 0$

$w_x = 0, w_y = 5x - 2.5$

2D tests to indifference to grid motion strategy



l 240x240

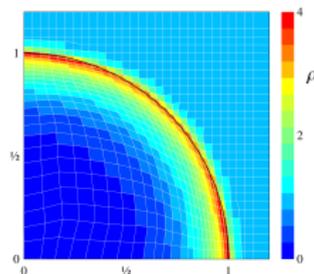
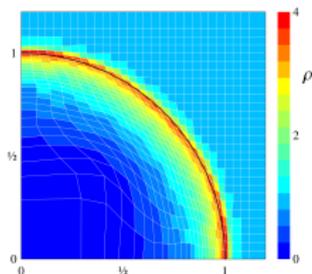
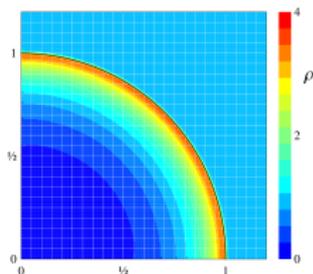
200x100

w $w_x = w_y = 0$

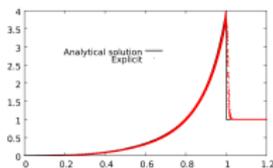
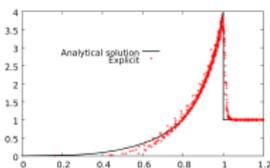
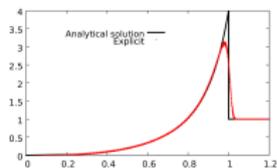
$w_x = y, w_y = 0$

2D illustrations of versatility in grid motion strategy

2D Sedov



Density



/ 240x240

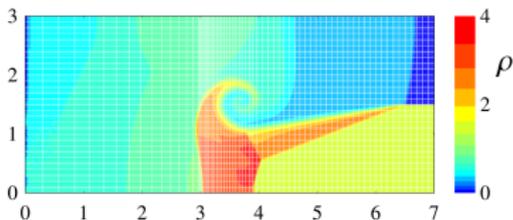
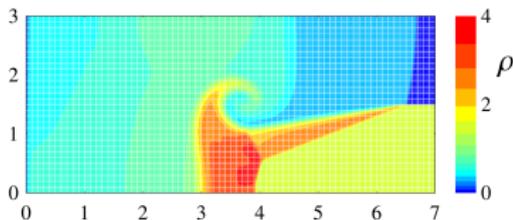
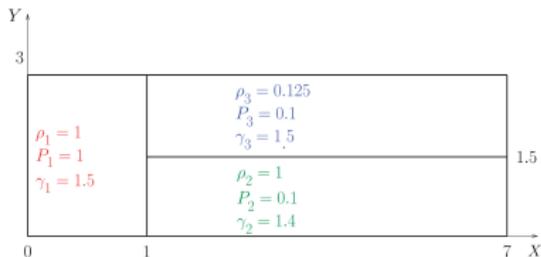
30x30

30x30

w 0

 $0,99\mu^{\text{Lag}}$ $\tau\mu^{\text{Lag}}$ with $\tau = (t/t_0)^2 / (1 + (t/t_0)^2)$

Initial conditions of Triple point test



l 700x300

700x300

w 0

$\langle \mu_x^{\text{Lag}} \rangle_{y \in [0, 1.5]}$

- ▶ Scientific context : ALE schemes and numerical mimetism
- ▶ Discrete derivation of the scheme
 - Discretization of fields and transport
 - Discrete action integral and Euler–Lagrange equations
 - Global strategy of derivation
 - Main steps of scheme
- ▶ Numerical tests
 - 1D indifference to implicit–explicit advection
 - 2D indifference to grid motion strategy
 - 1D–2D versatility in the choice of grid velocity
- ▶ Conclusions and perspectives

In this work, presentation of a novel 2D scheme for simulating single-fluid compressible flows :

- ▶ **Direct ALE formalism** → arbitrary evolution of grid
- ▶ **Mimetic approach** → capture of pressure work thermodynamically consistent
- ▶ **Exact conservation** of mass, momentum and total energy
- ▶ **Robustness and stability** in presence of shocks and deformations

Perspectives and current works :

- ▶ To be submitted soon
- ▶ Second-order accuracy
- ▶ Extension to multiple fluids ($N > 2$)
- ▶ Exchange terms for gas-particles flows